* Compare recent advancements in edge-preserving image filtering techniques, such as bilateral filters, anisotropic diffusion filters, and newer methods like guided filters and non-local means filters.
* Discuss the implications of advancements in edge-preserving image filtering techniques for improving patient outcomes and the overall quality of medical diagnostics.

**Bilateral filter**

It combines distance and range filters, assigning a weight depending not only on its spatial position relative to the central pixel but also on the similarity of its intensity compared to the value of the center pixel.

Impact: on a homogeneous region with similar intensities, bilateral filer is a linear weight average and similar intensity pixels on the edges are smoothed.

Gaussian functions with different standard deviations could be used for the domain which is proportional to the squared distance of pixel (x,y) s and another Gaussian represent the range filter and uses each coordinates.

**Advantages**

Robust, recommended approach for most of the applications

**Disadvantages**

Requires tuning of parameter σ.

When a pixel has few similar pixels around it (often on an edge), the Gaussian weighted average is unstable.

**Guided Filter**

For a given pixel, it found, in a guidance image G, the corresponding pixel and its corresponding spatial neighborhood:

* If the guidance image **G**, is the same as the input image to filter, the output image remains the same as the input image
* Otherwise, the output image is, locally, a linear transformation of the guidance image G. The linear optimization aims in minimizing the error (least squares method) between the output image and the input image.

**Advantages**

Parameter free, effective and efficient

**Disadvantages**

Can introduce blurry effects and artifacts

**Anisotropic Diffusion filter, Perona-Malik Filter**

It uses the diffusion equation, a partial differential equation which is nonlinear and space-variant, where intensities of the image are like the temperature which is modeled by the equation.

**Advantages**

It favors smoothing within regions of smoother intensity and suppress it across the edges, while at same time reduces the noise

**disadvantages**

The diffusion coefficient, (referred as K(x,t) in the course), can lead to instability: it can lead to backward diffusion that enhances contrast of image instead of smoothing it.

Pictures: images show a significant noise reduction ce between before and after. Edges and sharpness are preserved.

**Non-local Means Filter**

It is weighted average of the neighborhood pixels; in its initial implementation the weights are defined using a Gaussian applied to the difference of intensities of local neighborhood of the center pixel. Therefore, the weighting function is determined by the similarity between neighborhoods Other kernels like Turkey bi-weight, could be used to modify the weights more appropriately to include not only Euclidean difference in intensities but radiometric difference (color, depth distances, etc…).

**Advantages**

It removes the noise from the images and yet preserves the sharpness of strong edges. It also smooths textures.